## Logic Beyond Formulas: Designing Proof Systems on Graphs

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Keeping track of relations between objects or events is essential in modelling processes and in verifying their security and privacy properties. For this purpose, relations are encoded by means of formulas in order to use proof theoretical results to design verification tools.

However, relations admitting no series-parallel decomposition [6], which are ubiquitous in distributed systems, cannot be directly treated by the current proof theoretical methods. In fact, the natural correspondence between graphs and formulas (see [6, 11, 8]) fails as soon as simple topological conditions on graphs are not met.

By means of example, consider four processes a, b, c and d where communication between some processes is forbidden because of certain conflicts of interest [5]. Thus, the following pairs cannot communicate: a and b, a and d, and c and d, as shown in the graph below in the centre.

$$\begin{array}{c|c} a & b & a & b & a & b \\ \hline c & d & c & d & c & d \\ \hline \hline (a \lor c) \land (b \lor d) & \text{no formula} & (a \land b) \lor (c \land d) \end{array}$$
(1)

Another example is given by the causality patterns for *n*-queues, where *n* is the bound on the number of elements that can be enqueued represented by the graphs below, where nodes labelled by  $e_x$  and  $d_x$  respectively represent the enqueuing and dequeuing of the element *x* (we only represent the first three elements *a*, *b*, and *c* inserted into the queue).



The graphs  $Q_1$  and  $Q_2$  are series-parallel graphs and can be directly encoded as formulas. The graph  $Q_3$ , and more in general the causality patterns for *n*-queues with n > 2, cannot.

This contribution, based on joint works with Straßburger, Horne and Mauw [3, 2, 1], is an introduction on proof systems operating on graphs instead of formulas providing proof theoretical tools able to directly handle non series-parallel relations as primitive objects of a logic.

For this purpose, we use results on graph modular decomposition [10] to associate abstract syntax trees to graphs, allowing us to generalise the notions of connectives and subformulas to this new setting. We then define a linear implication  $\neg a$  and we define proof systems meeting certain basic desiderata such as the derivability of the general identity ( $G \neg G$  is provable for any graph G), and the transitivity of implication (if  $G \neg H$  and  $H \neg K$  are provable, then  $G \neg K$  also is). Our proof systems on graphs are presented using the open deduction [9] proof formalism (see Figure 1) based on deep inference [4] since, as observed for the non-commutative logic BV [8], it is not possible to define an analytic sequent calculus for these logics.



Figure 1: A proof of the graph  $Q_3 \rightarrow Q_2$  in the system GV<sup>sl</sup> serving as proof that 3-queues can simulate behaviours of 2-queues. The rule sl slices a directed graph into a "before" and an "after" part by introducing additional directed edges. The rule mq merges the modules of two copies of the same directed graph.

We present the system GS handling undirected graphs as the ones in (1). and we prove that GS is a conservative extension of the *multiplicative linear logic with mix* [7]. Then we present the systems GV and  $GV^{sl}$  handling graphs with both directed and undirected edges. These systems provide a conservative extension of both the graphical logic defined by GS and the non-commutative logic BV [8]. We present the technique developed to prove these results, including the challenges we encountered in proving the analogous of cut-elimination for deep inference systems in the graphical setting. We conclude by recalling related results in proof theory and concurrency theory, and giving an overview on the the ongoing researches on the topic.

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